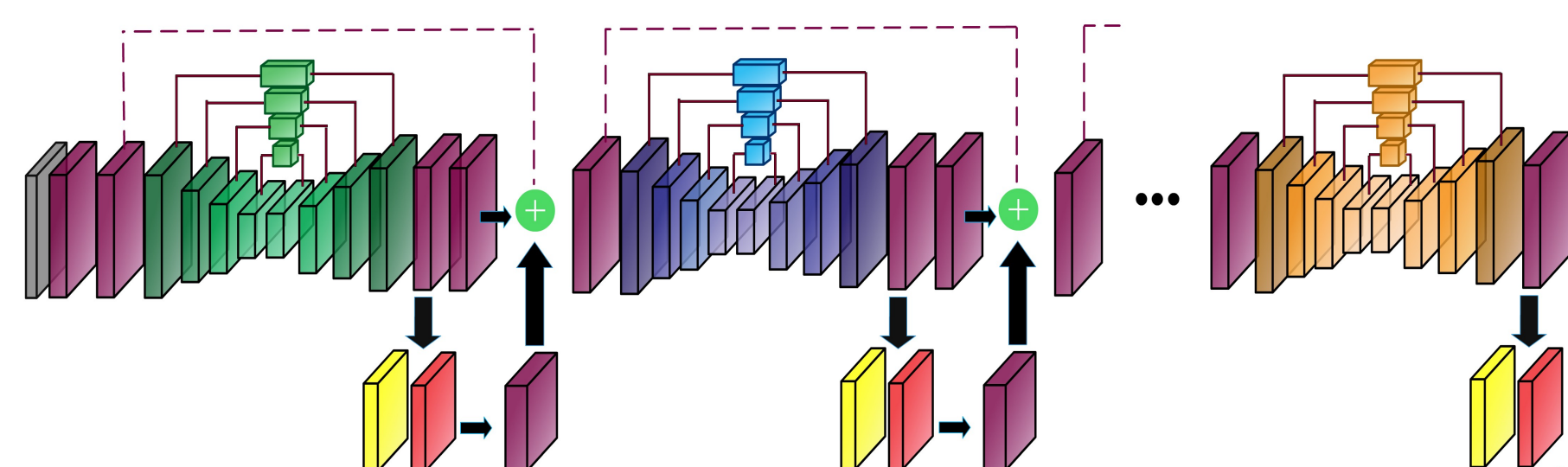


Objective

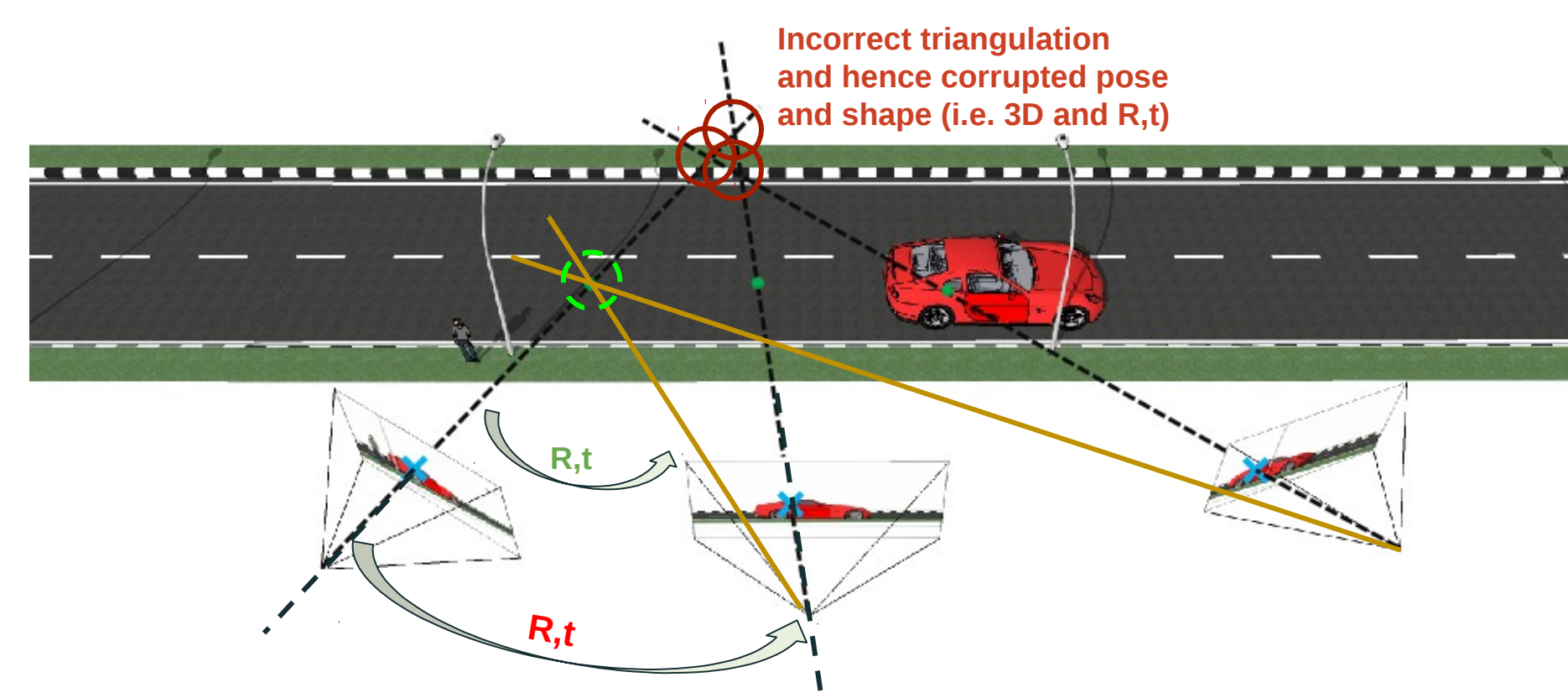
A monocular object localization system.

Estimates the **shape** and **pose** of **dynamic objects** in real-time, using video frames captured from a moving monocular camera.

CRF-Style Stacked Hourglass Networks



Why dynamic scenes are catastrophic ...



Qualitative Results



Keypoint Localization Results

